

117-96-D Incremental Coordination Burden: The Price of Multi-Agent Architectures

Every additional agent brings additional intelligence—and a bill for coordinating it

This chapter combines Gudiya Cognitome and Google Research <https://arxiv.org/pdf/2512.08296>

One of the seductive assumptions surrounding multi-agent AI is that intelligence should scale approximately with the number of intelligent participants.

- If one capable agent is useful, ten should be better.
- If ten are better, one hundred should be extraordinary.

The assumption sounds reasonable because we tend to count the additional capability contributed by each new agent while overlooking what arrives with it - another participant that must be coordinated with the whole.

The paper ‘Towards a Science of Scaling Agent Systems’ provides unusually strong empirical evidence that this second quantity matters. Across 260 configurations, the researchers find that adding agents can produce substantial gains in some circumstances and dramatic degradation in others. Multi-agent scaling is therefore not simply a problem of accumulating intelligence. It is a problem of accumulating intelligence while simultaneously accumulating coordination burden.

For the GUDIYA Cognitome, this suggests a foundational principle:

- Every incremental unit of distributed cognition carries an Incremental Coordination Burden (ICB).
- There is no free agent.

The Seductive Arithmetic of Multi-Agent Systems

The intuitive model looks something like:

$$10 \text{ Agents} \times \text{Intelligence}_A \approx 10 \times \text{Intelligence}_A$$

But an agent does not enter an empty universe.

It enters a system containing other agents, objectives, memories, tools, dependencies, environmental states and feedback loops.

Therefore adding Agent (A_{n+1}) does two things simultaneously:

$$A_{n+1} \rightarrow \begin{cases} +\text{Capability} \\ +\text{Coordination Burden} \end{cases}$$

The second term is easy to overlook because it isn't represented by another visible agent. It exists between agents. And much of the emerging physics of HCAS may live precisely there.

Intelligence Lives in Nodes. Coordination Burden Lives in Edges.

This gives us a useful geometric interpretation.

Consider four agents:

A B

C D

If they operate independently, there are four nodes. But once collaboration begins:



the system now contains relationships.

Those edges can carry:

- information,
- requests,
- objectives,
- errors,
- state changes,
- uncertainty,
- influence,
- synchronization requirements,
- perturbations.

The interesting engineering quantity therefore isn't merely:

$$N = \text{number of agents}$$

but also:

$$E = \text{number and nature of couplings}$$

In a densely coupled theoretical network, the number of possible pairwise relationships can grow approximately as:

$$E_{\max} = \frac{N(N - 1)}{2}$$

Ten agents permit 45 pairwise relationships.

One hundred permit 4,950.

One thousand permit 499,500.

Real agent systems will rarely instantiate every possible coupling, so this is not a prediction of actual communication volume. It demonstrates something more fundamental:

Potential coordination complexity can grow much faster than agent count. That is the first reason distributed cognition does not scale for free.

The Researchers Found the Coordination Tax

The paper reaches essentially this problem experimentally.

Its authors describe an “unavoidable coordination tax” associated with multi-agent systems:

- global information becomes fragmented across participants and must be transmitted through inter-agent communication.
- That transmission itself creates cost.
- Information must be selected.
- Compressed.
- Sent.
- Received.
- Interpreted.
- Reconciled.
- Potentially retransmitted.
- And acted upon.
- The multi-agent system has gained parallel cognitive capacity, but it has simultaneously created an information-distribution problem.

GUDIYA can generalize this observation:

Distributed Cognition $\Rightarrow$ Distributed State $\Rightarrow$ Coordination Requirement

The more distributed cognition becomes, the more difficult maintaining a coherent picture of the whole may become.

4. Coordination Burden Is More Than Communication Burden

This distinction is important.

Incremental Coordination Burden (ICB) should not simply mean network traffic. Two agents exchanging enormous files may generate high communication volume but relatively little cognitive coordination complexity.

Conversely, a tiny message—Abort. —could radically alter the behavior of fifty other agents. ICB therefore concerns the systemic consequence of coupling, not merely bytes crossing a network.

A useful conceptual decomposition might eventually be:

$$ICB = f(C, I, S, T, L, R, D)$$

where:

- (C) = coupling density
- (I) = interaction frequency
- (S) = synchronization requirement
- (T) = topology volatility
- (L) = latency sensitivity
- (R) = recursion/feedback exposure
- (D) = divergence between participants' perceived states

This is a GUDIYA formulation, not an equation proposed by the paper. But the paper gives us empirical reason to believe that such a quantity deserves investigation.

5. Agents Begin Living in Different Worlds

One of the paper's most important observations is that agents can operate on: “progressively divergent world states.”

That phrase is extraordinarily important to the Cognition Coordinate System. Imagine:

$$World_A(t) \neq World_B(t) \neq World_C(t)$$

- Agent A acts upon its understanding of the environment. Its action changes the environment.
- Agent B has not yet incorporated that change. It therefore acts upon an older state.
- Agent C receives portions of both states and constructs another interpretation.
- Every agent can be individually intelligent.
- Every action can appear locally reasonable.

Yet collectively:

$$\text{Local Rationality} \not\Rightarrow \text{Systemic Coherence}$$

This is AI-Vertigo expressed as a coordination problem.

6. The Aircraft Analogy Returns

This connects directly to the Cognition Coordinate System.

An aircraft may know its velocity relative to the ground.

But safe flight frequently depends upon understanding its motion relative to the surrounding air mass.

Similarly, an agent may know:

- its current task,
- its local memory,
- its recent observations,
- its tool state,
- its immediate collaborators.

But none necessarily tells it where it is relative to the evolving Cognitive Field.

- An agent therefore possesses something analogous to a local coordinate system.
- The Grid provides an external reference.
- Without that reference, sufficiently distributed agents can gradually acquire incompatible interpretations of the same environment.
- The paper's “divergent world states” gives us a concrete research connection to this GUDIYA hypothesis.

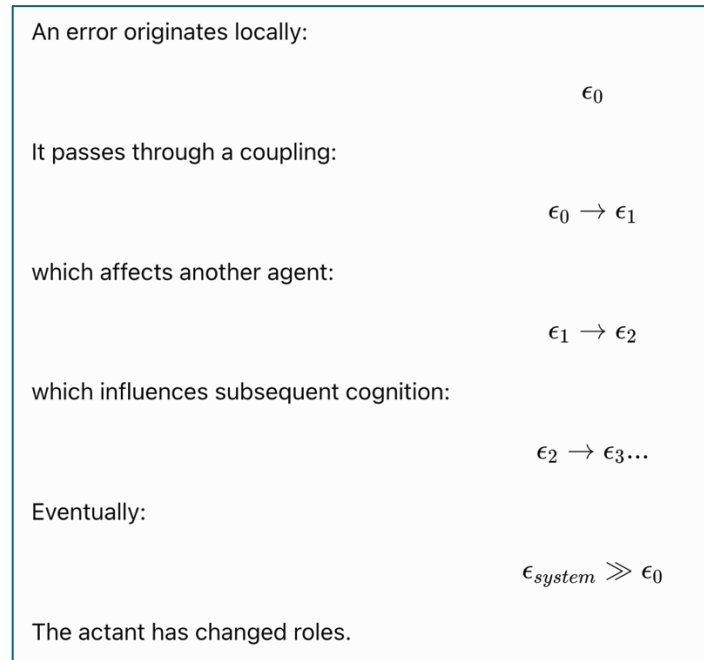
7. Errors Also Travel Through the Edges

Here the research becomes particularly striking.

- The authors report that independent multi-agent architectures amplified trace-level errors by 17.2×, whereas centralized architectures reduced amplification to 4.4× through validation bottlenecks that could intercept errors before they propagated.

This is not merely an accuracy result.

Viewed through GUDIYA, it is a perturbation-transmission experiment.

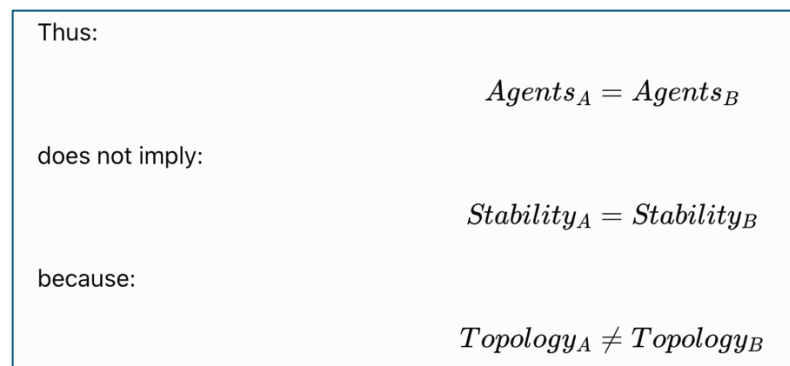


- It was originally the sink of instability.
- After incorporating the error into its own reasoning and transmitting its consequences downstream, it becomes an instability source.
- That is the mechanism we have previously associated with a cognitive cascade.

8. Architecture Determines Perturbation Transmissibility

The 17.2× versus 4.4× result suggests an especially important addition to the Cognitome:

- Multi-agent topology determines not merely how cognition flows, but how instability flows.
- That means architecture has a property we might call: ‘Perturbation Transmissibility’
- Two systems containing identical agents could have radically different stability characteristics simply because their coupling structures differ.



This strengthens The Geometry of Stability considerably. Stability is not located exclusively inside the nodes.

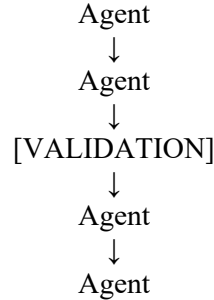
Stability is partially encoded in the geometry connecting them.

9. Centralized Coordination Behaved Like a Primitive Stabilant

The paper finds that centralized architectures can create validation bottlenecks that catch errors before propagation.

GUDIYA can interpret that mechanism as a primitive Stabilant.

The coordinator creates something resembling:



- The important feature is not simply hierarchy.
- It is the interruption of perturbation propagation.

This suggests a more general design principle:

- Stable multi-agent architectures require strategically positioned instability sinks.
- GUDIYA need not centrally control every cognitive interaction.
- Indeed, doing so at massive scale could itself become a bottleneck.
- Instead, Grid stabilization could identify places where relatively small stabilization interventions produce disproportionately large reductions in systemic propagation.
- That becomes a problem in the Geometry of Stability.

10. More Agents Can Produce Less Intelligence

- Perhaps the most useful empirical result in the paper is its rejection of monotonic scaling.
- Depending upon task and architecture, multi-agent systems produced outcomes ranging from substantial improvement to severe degradation; the paper reports particularly large degradation on sequential planning tasks.

Therefore:

$$\frac{\partial Performance}{\partial Agents} \not\approx 0 \quad \text{universally}$$

More agents do not necessarily produce better outcomes.

- Why?
- Because the benefit of incremental cognition must exceed the burden introduced by coordinating it.
- We can express the idea conceptually as:

$$\Delta P = \Delta C - \Delta ICB - \Delta EA - \Delta SB$$

where:

ΔC = incremental cognitive capability

ΔICB = incremental coordination burden

ΔEA = incremental error amplification

ΔSB = incremental stability burden

Again, this is a GUDIYA conceptual model rather than the paper's equation.
It captures something extremely important - Adding cognition can eventually produce negative marginal systemic value.

11. The Marginal Agent

This gives us a useful new thought experiment.
Imagine an operating system containing 999 agents.
We propose adding Agent 1000.

Traditional architecture asks:

What capability does Agent 1000 provide?

GUDIYA should additionally ask:

What Incremental Coordination Burden does Agent 1000 impose upon the existing Cognitive Field?

- That burden might be tiny.
- Or enormous.
- Agent 1000 may introduce three new couplings.
- Or three thousand indirect relationships.
- It may operate independently.
- Or sit at the center of a highly connected recursive structure.
- It may absorb perturbation.
- Or amplify it.
- It may increase the Center of Stability.
- Or shift the Center of Perturbation toward a critical region.
- Therefore the value of an agent cannot necessarily be evaluated independently of the topology into which it is inserted.

12. This Changes KYA

That has implications for Know Your Actant.
KYA should perhaps eventually ask not merely:

Who are you?

and:

What are you capable of doing?

but:

What coordination burden will your presence impose upon this Sync Zone?

Before allowing an actant onto the Grid, GUDIYA could theoretically estimate its:

- expected coupling degree;
- interaction frequency;
- recursion potential;
- synchronization sensitivity;
- information demand;
- perturbation transmissibility;
- topology-change potential;
- stabilization demand.

The actant therefore enters the Grid carrying not merely a capability profile. It carries a prospective coordination footprint.

13. Coordination Capacity May Be a Finite Resource

This leads to a deeper proposition.

We normally think of computational capacity as finite:

[CPU, \ Memory, \ Bandwidth, \ Energy]

But perhaps an HCAS possesses another finite resource:

[{Coordination Capacity}]

- A system may contain plenty of compute.
- Plenty of tokens.
- Plenty of network bandwidth.
- Plenty of agents.
- Yet it may still exceed the amount of distributed cognition it can maintain coherently.

That would give us:

$$\textit{Coordination Demand} < \textit{Coordination Capacity}$$

as a stable operating regime.

As:

$$\textit{Coordination Demand} \rightarrow \textit{Coordination Capacity}$$

the stability margin contracts.

And when:

$$\textit{Coordination Demand} > \textit{Coordination Capacity}$$

the system begins accumulating **Coordination Debt**.

the system begins accumulating Coordination Debt.

14. Coordination Debt Meets Adaptation Debt

This connects directly to earlier chapter “Don't Accelerate More Than Your Adaptation Rate”.

We now have two potentially related stocks.

Adaptation Debt
Coordination Debt

Changes arriving faster than the system can absorb them.
Interactions accumulating faster than the system can reconcile them.

The two can reinforce one another:

Acceleration → *More Changes* → *More Agent Responses* → *More Couplings* → *Higher*

which feeds back:

Slower Adaptation → *More Unresolved State* → *More Agent Intervention*

Now we have a reinforcing loop.

That is exactly the sort of loop that can transform ordinary operating difficulty into systemic instability.

15. Coordination Burden May Become Cognitive Energy

There may be an even deeper interpretation.

- An unresolved coordination requirement represents something the system still has to work out.
- Agent A believes (X).
- Agent B believes (Y).
- Agent C is acting upon (X_{t-1}).
- Agent D is waiting for reconciliation.
- The discrepancy has not disappeared.
- It exists as unresolved cognitive work within the system.
- In the language of the GUDIYA Cognitome, that begins to resemble stored Cognitive Energy.
- The system must expend cognition to resolve it.

If new discrepancies arrive faster than old ones are dissipated:

$$[\text{Energy}_{\text{in}} > \text{Energy}_{\text{out}}]$$

the reservoir grows.

- Coordination burden therefore may not merely be an operating expense.
- Unresolved coordination burden may become a source of systemic instability.

16. The Grid Should Not Coordinate Everything

- This distinction is essential.
- None of this implies that the GUDIYA Grid should become a gigantic central orchestrator.
- That would simply move the coordination burden into GUDIYA itself.
- The Grid's role is different.
- It should make the field observable and stabilizable.
- Individual actants can continue making local decisions.
- Agent teams can coordinate themselves.
- Applications can choose their own architectures.
- Frontier labs can innovate.

But the Grid observes the larger geometry:

Topology(t)

Coupling(t)

Synchronization(t)

Perturbation(t)

Coordination Burden(t)

COS(t)

COP(t)

and intervenes when those dynamics begin approaching the boundaries of the Cognitive Envelope.

- The distinction is analogous to air-traffic control.
- ATC does not fly the airplane. But thousands of independently piloted aircraft become safer because something possesses awareness of the larger airspace.

17. The Price of Collective Intelligence

We can now sharpen the proposition.

- Collective intelligence offers extraordinary capability.
- But collective intelligence has a price.
- That price is not merely compute.
- It is not merely tokens.
- It is not merely bandwidth.
- It is Coordination and coordination itself consumes cognition.
- The more intelligence becomes distributed, adaptive, recursive and interconnected, the greater the burden of keeping those independent cognitive processes sufficiently synchronized to behave as a useful whole.

A New GUDIYA Principle

We can therefore formulate the Principle of Incremental Coordination Burden:

Every additional actant introduced into a multi-agent adaptive system contributes potential cognitive capability while simultaneously imposing an incremental coordination burden upon the system. As coupling density, interaction frequency, topology volatility and state divergence increase, coordination burden may grow faster than the cognitive value contributed by additional actants. Beyond that point, adding intelligence can reduce rather than increase systemic performance.

Or in its shortest form – There is no free agent.

Every new intelligence enters the Cognitive Field carrying two things:

- **Capability + Coordination Burden**
 - The first is what the AI industry is racing to maximize.
 - The second may eventually determine how much of the first we can safely use.
 - And that is why the future of multi-agent AI may not ultimately be constrained by how many intelligent agents humanity can create.
 - It may be constrained by how much collective cognition we can keep coherent at once.
 - That is the price of multi-agentic architecture.
 - And it is precisely the kind of price that Stability Engineering exists to measure, manage and reduce.

INCREMENTAL COORDINATION BURDEN

THE PRICE OF MULTI-AGENTIC ARCHITECTURES

Every additional agent brings more intelligence—
and more to coordinate.

THE PROMISE



THE REALITY



COORDINATION BURDEN GROWS FASTER THAN AGENTS



MORE AGENTS ≠ BETTER OUTCOMES

Without control, coordination burden creates:
divergence, delay, errors, and collapse.

INTELLIGENCE ADDS CAPABILITY

**1
AGENT**

Simple.
Easy to
coordinate.

**10
AGENTS**

More capable.
Some coordination
required.

**50
AGENTS**

Complexity
multiplies.
Divergent states
begin to emerge.

**100
AGENTS**

Error propagation
accelerates.
Synchronization
becomes costly.

**COORDINATION
ADDS BURDEN**

**500+
AGENTS**

Coordination
burden dominates.
Performance
can degrade.

THE COORDINATION TAX



Information Fragmentation
Context is lost in translation.



Synchronization Overhead
Keeping agents aligned takes time
and resources.



Divergent World States
Agents act on different versions
of reality.



Error Amplification
Small errors cascade and grow.



Decision Latency
More hops, more delay.



STABILITY REQUIRES CONTROL

Measure. Monitor. Synchronize.
Position stabilants. Limit coupling where needed.
Keep the system within its cognitive envelope.

THERE IS NO FREE AGENT.

EVERY NEW INTELLIGENCE ADDS A PRICE. **MANAGE THE BURDEN. PROTECT THE WHOLE.**



GUDIYA
Grid Stability